



## On the Arithmetic Mean Estimators of a Family of Estimators of Finite Population Variance of Ratio Type

MOJEED ABIODUN YUNUSA<sup>1</sup>, AHMED AUDU<sup>1</sup> and JAMIU OLASUNKANMI MUILI<sup>2\*</sup>

<sup>1</sup>Department of Statistics, Usmanu Danfodiyo University, Sokoto, Nigeria.

<sup>2</sup>Department of Mathematics, Kebbi State University of Science and Technology Aliero, Nigeria.

### Abstract

For many years, one of the difficult components of sampling theory has been the estimation of population characteristics, especially variance. The estimation of variability is very essential in many fields (Chemistry, Biology, Mathematics, and so on) to know how one quantity varies with respect to another quantity. This paper proposes arithmetic estimators of a group of ratio estimators for populations with finite variance. Using a Taylor series technique, the bias and MSE of the proposed estimators are determined up to the first order of approximation together with the efficiency conditions overexisting estimators. The effectiveness of the proposed estimators in comparison to the current estimators is evaluated using a real-world data set. The empirical findings demonstrate that the suggested estimators outperform the current estimators taken into account in the study. Hence, these suggested estimators are recommended for use in real life scenario.



### Article History

Received: 03 August 2022

Accepted: 20 October 2022

### Keywords:

Arithmetic Mean;  
Bias; Efficiency;  
Mean Square Error;  
Ratio estimator.

### Introduction

Isaki<sup>1</sup> was the first to discuss the issue of estimates of population variance when auxiliary variable is present and proposed the classical ratio method of estimation for population variance which utilize the ratio population and sample variance of auxiliary variable as auxiliary information which is strongly correlated with the study variable. Numerous authors have modified ratio estimators for finite population variance when an auxiliary variable is present in the literature, authors like Evans,<sup>3</sup> Hansen

and Hurwitz,<sup>5</sup> Prasad and Singh.<sup>14</sup> Prasad and Singh<sup>14</sup> modified the work of Isaki<sup>6</sup> by incorporating coefficient of kurtosis into his work. Ever since then several authors have been making efforts to develop estimators with greater efficiency using auxiliary information for improvement and modification, other authors include Kadilar and Cingi,<sup>7</sup> Gupta and Shabbir,<sup>4</sup> Tailor and Sharma,<sup>16</sup> Khan and Shabbir,<sup>8</sup> Yadav *et al.*,<sup>17</sup> Subramani,<sup>15</sup> Audu *et al.*,<sup>1</sup> Maqbool and Shakeel,<sup>9</sup> Muili *et al.*,<sup>12,11</sup> Bhat *et al.*,<sup>2</sup> and Muili *et al.*<sup>10</sup> Muili *et al.*<sup>10</sup> modified the work of Bhat

**CONTACT** Jamiu Olasunkanmi Muili ✉ [jamiunice@yahoo.com](mailto:jamiunice@yahoo.com) 📍 Department of Mathematics, Kebbi State University of Science and Technology Aliero, Nigeria.



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Doi: <http://dx.doi.org/10.13005/OJPS07.02.03>



et al.<sup>2</sup> by incorporating First quartile, Downton's method, Deciles, Mid-range and Percentiles into the developed estimators for the purposed of precision.

To provide estimates that are closer to the population mean of the study variable, we proposed arithmetic mean estimators from a family of ratio type estimators of finite population variance in this study.

Consider a finite population  $G=\{G_1, G_2, \dots, G_N\}$ , a set of N units, where  $G_i=\{X_i, Y_i\}$ ,  $i = 1, 2, \dots, N$  has a pair values. Y is the study variable and is associated with the auxiliary variable X, where  $Y=\{Y_1, Y_2, \dots, Y_N\}$  and  $x=\{x_1, x_2, \dots, x_N\}$  are the n sample values. The sample means for the study and the auxiliary variables are  $\bar{y}$  and  $\bar{x}$ , respectively.  $S_x^2$  and  $S_y^2$  are the population mean squares of X and Y respectively and  $s_x^2$  and  $s_y^2$  represent the sample mean square for the size n randomly selected, without replacement. Y: Study variable, n: sample size, N: population size, X: Auxiliary variable,  $\bar{x}, \bar{y}$ : Auxiliary and study variables sample means,  $\bar{x}, \bar{y}$ : Auxiliary and study variables population means, f: Sampling fraction,  $\rho$ : Correlation coefficient,  $C_y, C_x$ : Coefficient of variation of study and auxiliary variable,  $\beta_{1(x)}$ : Skewness,  $Q_1$ : First quartile of auxiliary variable,  $Q_2$ : Second quartile,  $Q_3$ : Third quartile, QD: Quartile deviation,  $\beta_{2(x)}$ : Kurtosis, TM: Tri-mean,  $M_d$ : Median of auxiliary variable,  $M_x$ : Maximum value of auxiliary variable,  $Q_i$ : Hodges lehman estimator, MR: Population mid-range of auxiliary variable,  $Q_i$ : Downton's method,  $P_i$ : Percentile of auxiliary variable.

$$\bar{Y} = \frac{1}{N} \sum_{i=1}^N Y_i, \bar{X} = \frac{1}{N} \sum_{i=1}^N X_i, \bar{y} = \frac{1}{n} \sum_{i=1}^n y_i, \bar{x} = \frac{1}{n} \sum_{i=1}^n x_i, \gamma = \frac{1-f}{n}, f = \frac{n}{N}$$

$$MR = \frac{X_{(1)} + X_{(2)}}{2}$$

$$TM = \frac{Q_1 + 2Q_2 + Q_3}{4}, S_y^2 = \frac{1}{N} \sum_{i=1}^N (Y_i - \bar{Y})^2, S_x^2 = \frac{1}{N} \sum_{i=1}^N (X_i - \bar{X})^2$$

$$s_x^2 = \frac{1}{n-1} \sum_{i=1}^n (y_i - \bar{y})^2, s_y^2 = \frac{1}{n-1} \sum_{i=1}^n (x_i - \bar{x})^2$$

$$HL = Median \left( \frac{X_i + X_j}{2}, i \leq i \leq j \leq N \right)$$

$$D = \frac{2\sqrt{\pi}}{N(N-1)} \sum_{i=1}^N \left( i - \frac{N+1}{2} \right) X_i$$

**Literature Review**

The population's variance's unbiased estimator is  $t_o = S_y^2$  ... (1)

The estimator's bias and mean square error (Variance) are provided by

$$Bias(t_o) = 0 \quad \dots(2)$$

$$Var(t_o) = \gamma S_y^4 (\beta_{2(y)} - 1) \quad \dots(3)$$

When the population and sample variance of the auxiliary variable are available, Isaki<sup>6</sup>'s proposed ratio estimator for estimating population variance of the study variable is defined as

$$t_R = s_y^2 \left( \frac{S_x^2}{s_x^2} \right) \quad \dots(4)$$

The estimator's  $t_R$  bias and mean square error are

$$Bias(t_R) = \gamma S_y^2 \left( (\beta_{2(x)} - 1) - (\lambda_{22} - 1) \right) \quad \dots(5)$$

$$MSE(t_R) = \gamma S_y^4 \left( (\beta_{2(y)} - 1) + (\beta_{2(x)} - 1) - 2(\lambda_{22} - 1) \right) \quad \dots(6)$$

Kadilar and Cingi<sup>7</sup> developed class of ratio estimators taking into account the coefficient of variation and kurtosis of the auxiliary variable as auxiliary information for improvement in the estimation of population variance and it is defined as

$$t_{KCI} = s_y^2 \left( \frac{S_x^2 + I_i}{s_x^2 + I_i} \right), \quad i = 1, 2, 3, 4 \quad \dots(7)$$

The estimator's  $t_{KCI}$  bias and mean square error are,

$$Bias(t_{KCI}) = \gamma L_i S_y^2 \left( L_i (\beta_{2(x)} - 1) - (\lambda_{22} - 1) \right), \quad i = 1, 2, 3, 4 \quad \dots(8)$$

$$MSE(t_{KCI}) = \gamma S_y^4 \left( (\beta_{2(y)} - 1) + L_i^2 (\beta_{2(x)} - 1) - 2L_i (\lambda_{22} - 1) \right), \quad i = 1, 2, 3, 4 \quad \dots(9)$$

where,  $I_1 = C_x, I_2 = \beta_{2(x)}, I_4 = \beta_{2(x)} / C_x, I_3 = C_x / \beta_{2(x)}$ ,

$$L_i = \frac{S_x^2}{S_x^2 + I_i}, \quad i = 1, 2, 3, 4.$$

Subramani<sup>15</sup> developed a generalized modified ratio estimator that uses the median and coefficient of variation of the auxiliary variable to estimate the finite population variance of the study variable in order to enhance the precision of the estimate as.

$$t_s = s_y^2 \left( \frac{S_x^2 + k}{s_x^2 + k} \right) \quad \dots(10)$$

The estimator's  $t_s$  bias and mean square error are,

$$Bias(t_s) = \gamma K S_y^2 \left( K (\beta_{2(x)} - 1) - (\lambda_{22} - 1) \right) \quad \dots(11)$$

$$MSE(t_s) = \gamma S_y^4 \left( (\beta_{2(y)} - 1) + K^2 (\beta_{2(x)} - 1) - 2K (\lambda_{22} - 1) \right) \quad \dots(12)$$

where,  $k = M_d / C_x$ ,  $K = \frac{S_x^2}{S_x^2 + k}$ .

Bhat et al.<sup>2</sup> modified robust estimators for the estimation of population variance utilizing a linear combination of Downton's approach and deciles of the auxiliary variable in order to improve the precision of the estimate as well as the estimation of the study's finite population variance.

$$t_{Bi} = s_y^2 \left( \frac{S_x^2 + b_i}{s_x^2 + b_i} \right), \quad i = 1, 2, \dots, 10 \quad \dots(13)$$

The estimator's  $t_{Bi}$  bias and mean square error are

$$Bias(t_{Bi}) = \gamma B_i S_y^2 \left( B_i (\beta_{2(x)} - 1) - (\lambda_{22} - 1) \right), \quad i = 1, 2, \dots, 10 \quad \dots(14)$$

$$MSE(t_{Bi}) = \gamma S_y^4 \left( (\beta_{2(y)} - 1) + (B_i (\beta_{2(x)} - 1) - 2(\lambda_{22} - 1)) \right), \quad i = 1, 2, 3, 4 \quad \dots(15)$$

where,  $b_1 = (D+D_1)$ ,  $b_2 = (D+D_2)$ ,  $b_3 = (D+D_3)$ ,  $b_4 = (D+D_4)$ ,  $b_5 = (D+D_5)$ ,  $b_6 = (D+D_6)$ ,  $b_7 = (D+D_7)$ ,  $b_8 = (D+D_8)$ ,  $b_9 = (D+D_9)$ ,  $b_{10} = (D+D_{10})$ ,

$$B_i = \frac{S_x^2}{S_x^2 + b_i}, \quad i = 1, 2, \dots, 10$$

Muili et al.<sup>10</sup> developed a family of ratio type estimators for finite population variance estimation utilizing the parameters of the auxiliary variable, first quartile, downton's method, deciles, mid-range and percentiles as

$$t_{ji} = s_y^2 \left( \frac{S_x^2 + h_i}{s_x^2 + h_i} \right), \quad i = 1, 2, \dots, 21 \quad \dots(16)$$

The estimator's  $t_{ji}$  bias and mean square error are:

$$Bias(t_{ji}) = \gamma H_i S_y^2 \left( H_i (\beta_{2(x)} - 1) - (\lambda_{22} - 1) \right), \quad i = 1, 2, \dots, 21 \quad \dots(17)$$

$$MSE(t_{ji}) = \gamma S_y^4 \left( (\beta_{2(y)} - 1) + H_i^2 (\beta_{2(x)} - 1) - 2H_i (\lambda_{22} - 1) \right), \quad i = 1, 2, \dots, 21 \quad \dots(18)$$

Where,  $h_1 = (D_{10}+P_1)$ ,  $h_2 = (D_{10}+P_5)$ ,  $h_3 = (D_{10}+P_{10})$ ,  $h_4 = (D_{10}+P_{15})$ ,  $h_5 = (D_{10}+P_{20})$ ,  $h_6 = (D_{10}+P_{25})$ ,  $h_7 = (D_{10}+P_{30})$ ,  $h_8 = (D_{10}+P_{35})$ ,  $h_9 = (D_9+P_{40})$ ,  $h_{10} = (MR+P_{45})$ ,  $h_{11} = (MR+P_{50})$ ,  $h_{12} = (MR+P_{55})$ ,  $h_{13} = (MR+P_{60})$ ,  $h_{14} = (MR+P_{65})$ ,  $h_{15} = (\bar{X}+P_{70})$ ,  $h_{16} = (\bar{X}+P_{75})$ ,  $h_{17} = (D+P_{18})$ ,  $h_{18} = (D+P_{85})$ ,  $h_{19} = (D+P_{19})$ ,  $h_{20} = (D+P_{95})$ ,  $h_{21} = (Q+P_{99})$

$$H_i = \frac{S_x^2}{S_x^2 + h_i}, \quad i = 1, 2, \dots, 21.$$

**Proposed Estimators**

We proposed arithmetic mean estimators of family of ratio type estimators of finite population variance when correlation between study and auxiliary variable is either positive or negative after studying and being inspired by Muili et al.<sup>10</sup>'s work.

$$t_{.41} = 2^{-1} (1 + z_1) s_y^2 \left( \frac{S_x^2 + (D_{10} + P_1)}{s_x^2 + (D_{10} + P_1)} \right) \quad \dots(19)$$

$$t_{.42} = 2^{-1} (1 + z_2) s_y^2 \left( \frac{S_x^2 + (D_{10} + P_5)}{s_x^2 + (D_{10} + P_5)} \right) \quad \dots(20)$$

$$t_{.43} = 2^{-1} (1 + z_3) s_y^2 \left( \frac{S_x^2 + (D_{10} + P_{10})}{s_x^2 + (D_{10} + P_{10})} \right) \quad \dots(21)$$

$$t_{.44} = 2^{-1} (1 + z_4) s_y^2 \left( \frac{S_x^2 + (D_{10} + P_{15})}{s_x^2 + (D_{10} + P_{15})} \right) \quad \dots(22)$$

$$t_{.45} = 2^{-1} (1 + z_5) s_y^2 \left( \frac{S_x^2 + (D_{10} + P_{20})}{s_x^2 + (D_{10} + P_{20})} \right) \quad \dots(23)$$

$$t_{.46} = 2^{-1} (1 + z_6) s_y^2 \left( \frac{S_x^2 + (D_{10} + P_{25})}{s_x^2 + (D_{10} + P_{25})} \right) \quad \dots(24)$$

$$t_{.47} = 2^{-1} (1 + z_7) s_y^2 \left( \frac{S_x^2 + (D_{10} + P_{30})}{s_x^2 + (D_{10} + P_{30})} \right) \quad \dots(25)$$

$$t_{.48} = 2^{-1} (1 + z_8) s_y^2 \left( \frac{S_x^2 + (D_{10} + P_{35})}{s_x^2 + (D_{10} + P_{35})} \right) \quad \dots(26)$$

$$t_{.49} = 2^{-1} (1 + z_9) s_y^2 \left( \frac{S_x^2 + (D_9 + P_{40})}{s_x^2 + (D_9 + P_{40})} \right) \quad \dots(27)$$

$$t_{.410} = 2^{-1} (1 + z_{10}) s_y^2 \left( \frac{S_x^2 + (MR + P_{45})}{s_x^2 + (MR + P_{45})} \right) \quad \dots(28)$$

$$t_{.411} = 2^{-1} (1 + z_{11}) s_y^2 \left( \frac{S_x^2 + (MR + P_{50})}{s_x^2 + (MR + P_{50})} \right) \quad \dots(29)$$

$$t_{.412} = 2^{-1} (1 + z_{12}) s_y^2 \left( \frac{S_x^2 + (MR + P_{55})}{s_x^2 + (MR + P_{55})} \right) \quad \dots(30)$$

$$t_{.413} = 2^{-1} (1 + z_{13}) s_y^2 \left( \frac{S_x^2 + (MR + P_{60})}{s_x^2 + (MR + P_{60})} \right) \dots(31)$$

$$t_{.414} = 2^{-1} (1 + z_{14}) s_y^2 \left( \frac{S_x^2 + (MR + P_{65})}{s_x^2 + (MR + P_{65})} \right) \dots(32)$$

$$t_{.415} = 2^{-1} (1 + z_{15}) s_y^2 \left( \frac{S_x^2 + (\bar{X} + P_{70})}{s_x^2 + (\bar{X} + P_{70})} \right) \dots(33)$$

$$t_{.416} = 2^{-1} (1 + z_{16}) s_y^2 \left( \frac{S_x^2 + (\bar{X} + P_{75})}{s_x^2 + (\bar{X} + P_{75})} \right) \dots(34)$$

$$t_{.417} = 2^{-1} (1 + z_{17}) s_y^2 \left( \frac{S_x^2 + (D + P_{80})}{s_x^2 + (D + P_{80})} \right) \dots(35)$$

$$t_{.418} = 2^{-1} (1 + z_{18}) s_y^2 \left( \frac{S_x^2 + (D + P_{85})}{s_x^2 + (D + P_{85})} \right) \dots(36)$$

$$t_{.419} = 2^{-1} (1 + z_{19}) s_y^2 \left( \frac{S_x^2 + (D + P_{90})}{s_x^2 + (D + P_{90})} \right) \dots(37)$$

$$t_{.420} = 2^{-1} (1 + z_{20}) s_y^2 \left( \frac{S_x^2 + (D + P_{95})}{s_x^2 + (D + P_{95})} \right) \dots(38)$$

$$t_{.421} = 2^{-1} (1 + z_{21}) s_y^2 \left( \frac{S_x^2 + (Q_1 + P_{99})}{s_x^2 + (Q_1 + P_{99})} \right) \dots(39)$$

The suggested estimators can be expressed generally as follows,

$$t_{.4i} = 2^{-1} (1 + z_i) s_y^2 \left( \frac{S_x^2 + h_i}{s_x^2 + h_i} \right), \quad i = 1, 2, \dots, 21 \dots(40)$$

**Properties (Bias and MSE) of the Proposed Estimators**

To derive the bias and MSE of the proposed estimators we use the following definitions e's sampling errors as

$$e_0 = \frac{s_y^2 - S_y^2}{S_y^2} \text{ and } e_0 = \frac{s_y^2 - S_y^2}{S_y^2} \text{ such that } s_x^2 = S_x^2 (1 + e_1)$$

$$\text{and } s_x^2 = S_x^2 (1 + e_1),$$

$$E(e_0) = E(e_1) = 0, \quad E(e_0^2) = \gamma(\beta_{2(y)} - 1), \quad E(e_1^2) = \gamma(\beta_{2(x)} - 1) \text{ and}$$

$$E(e_0 e_1) = \gamma(\lambda_{22} - 1)$$

Expressing (40) in terms of sampling errors, we have

$$t_{.4i} = 2^{-1} (1 + z_i) S_y^2 (1 + e_0) \left( \frac{S_x^2 + h_i}{S_x^2 (1 + e_1) + h_i} \right) \dots(41)$$

$$t_{.4i} = 2^{-1} (1 + z_i) S_y^2 (1 + e_0) \left( \frac{S_x^2 + h_i}{S_x^2 + h_i + S_x^2 e_1} \right) \dots(42)$$

$$t_{.4i} = 2^{-1} (1 + z_i) S_y^2 (1 + e_0) (1 + \Delta_i e_1)^{-1} \dots(43)$$

$$\text{Where, } \Delta_i = \frac{S_x^2}{S_x^2 + h_i}, \quad i = 1, 2, \dots, 21$$

By simplifying (43) up to first order approximation, we have

$$t_{.4i} = 2^{-1} (1 + z_i) S_y^2 (1 + e_0) (1 - \Delta_i e_1 + \Delta_i^2 e_1^2) \dots(44)$$

By expanding, simplifying and subtracting  $S_y^2$  from both sides of (44), we have

$$t_{.4i} - S_y^2 = S_y^2 \left( (1 + z_i) \left( \frac{1 + e_0 - \Delta_i e_1 + \Delta_i^2 e_1^2 - \Delta_i e_0 e_1}{2} \right) - 1 \right) \dots(45)$$

By taking the expectations from both sides of (45), one may get the estimator's  $t_{.4i}$  bias as

$$E(t_{.4i} - S_y^2) = S_y^2 E \left( (1 + z_i) \left( \frac{1 + e_0 - \Delta_i e_1 + \Delta_i^2 e_1^2 - \Delta_i e_0 e_1}{2} \right) - 1 \right) \dots(46)$$

$$\text{Bias}(t_{.4i}) = S_y^2 \left( 2^{-1} (1 + z_i) \left[ 1 + \gamma \left( \Delta_i^2 (\beta_{2(x)} - 1) - \Delta_i (\lambda_{22} - 1) \right) \right] - 1 \right) \dots(47)$$

The MSE of  $t_{.4i}$  is obtained by squaring both sides of (45) and taking expectation.

$$MSE(t_{.4i}) = S_y^4 \left( \frac{1 + (1 + z_i)^2 \left( \frac{1 + \gamma \left[ (\beta_{2(y)} - 1) + 3\Delta_i^2 (\beta_{2(x)} - 1) - 4\Delta_i (\lambda_{22} - 1) \right]}{4} \right)}{(1 + z_i) \left[ 1 + \gamma \left( \Delta_i^2 (\beta_{2(x)} - 1) - \Delta_i (\lambda_{22} - 1) \right) \right]} \right) \dots(48)$$

By solving for  $z_i$  and differentiating (48) with respect to equating zero, we obtain

$$z_i = \frac{2A_i}{B_i} - 1, \quad i = 1, 2, \dots, 21 \dots(49)$$

where,  $A_i = 1 + \gamma \left[ \Delta_i^2 (\beta_{2(x)} - 1) - \Delta_i (\lambda_{22} - 1) \right]$  and

$$B_i = 1 + \gamma \left[ (\beta_{2(y)} - 1) + 3\Delta_i^2 (\beta_{2(x)} - 1) - 4\Delta_i (\lambda_{22} - 1) \right]$$

By substituting (49) into (48), getting the estimator's minimum MSE  $t_{.4i}$  as

$$MSE(t_{.4i})_{\min} = S_y^2 \left( 1 - \frac{A_i^2}{B_i} \right), \quad i = 1, 2, \dots, 21 \dots(50)$$

**Efficiency Comparisons**

The proposed estimators  $t_{.4i}$  are more efficient than the existing estimators, if the following conditions are satisfied

$$MSE(t_{.4i})_{\min} < Var(t_0), \text{ if}$$

$$\gamma^{-1} \left( 1 - \frac{A_i^2}{B_i} \right) < (\beta_{2(y)} - 1) \quad \dots(51)$$

$MSE(t_{Ai})_{\min} < MSE(t_R)$  , if

$$\gamma^{-1} \left( 1 - \frac{A_i^2}{B_i} \right) - (\beta_{2(y)} - 1) < ((\beta_{2(x)} - 1) - 2(\lambda_{22} - 1)) \quad \dots(52)$$

$MSE(t_{Ai})_{\min} < MSE(t_{KCI})$  , if

$$\gamma^{-1} \left( 1 - \frac{A_i^2}{B_i} \right) - (\beta_{2(y)} - 1) < L_i (L_i (\beta_{2(x)} - 1) - 2(\lambda_{22} - 1)) \quad \dots(53)$$

$MSE(t_{Ai})_{\min} < MSE(t_S)$  , if

$$\gamma^{-1} \left( 1 - \frac{A_i^2}{B_i} \right) - (\beta_{2(y)} - 1) < K (K (\beta_{2(x)} - 1) - 2(\lambda_{22} - 1)) \quad \dots(54)$$

$MSE(t_{Ai})_{\min} < MSE(t_{Bi})$  , if

$$\gamma^{-1} \left( 1 - \frac{A_i^2}{B_i} \right) - (\beta_{2(y)} - 1) < B_i (B_i (\beta_{2(x)} - 1) - 2(\lambda_{22} - 1)) \quad \dots(55)$$

$MSE(t_{Ai})_{\min} < MSE(t_{Ji})$  , if

$$\gamma^{-1} \left( 1 - \frac{A_i^2}{B_i} \right) - (\beta_{2(y)} - 1) < H_i (H_i (\beta_{2(x)} - 1) - 2(\lambda_{22} - 1)) \quad \dots(56)$$

**Empirical Study**

To evaluate the effectiveness of the proposed estimators over existing ones, empirical study is carried out using a real life data set as

**Data**

**[Source: {Murthy,<sup>13</sup> P.228}**

X: Fixed capital

Y: Output of Eighty factories

N=80, n=20,  $S_y = 18.3569$ ,  $S_x = 8.4542$ ,  $C_y = 0.3542$ ,  $C_x = 0.7507$ ,  $\bar{Y} = 51.8264$ ,  $\bar{X} = 11.2624$ ,  $\beta_{2(y)} = 2.2667$ ,  $\beta_{2(x)} = 2.8664$ ,  $\beta_{1(x)} = 1.05$ ,  $p = 0.9413$ ,  $\lambda_{22} = 2.2209$ ,  $Q_1 = 9.318$ ,  $Q_2 = 7.575$ ,  $Q_3 = 16.975$ ,  $D = 8.0138$ ,  $MR = 17.955$ ,  $D_1 = 3.6$ ,  $D_2 = 4.6$ ,  $D_3 = 5.9$ ,  $D_4 = 6.7$ ,  $D_5 = 7.5$ ,  $D_6 = 8.5$ ,  $D_7 = 14.8$ ,  $D_8 = 18.1$ ,  $D_9 = 25$ ,  $D_{10} = 34.8$ ,  $P_1 = 2.44$ ,  $P_5 = 4.35$ ,  $P_{10} = 5.9$ ,  $P_{15} = 6.63$ ,  $P_{20} = 7.45$ ,  $P_{25} = 7.8$ ,  $P_{30} = 8.7$ ,  $P_{35} = 11.6$ ,  $P_{40} = 15.3$ ,  $P_{50} = 17.2$ ,  $P_{55} = 19.3$ ,  $P_{60} = 21.7$ ,  $P_{65} = 23.55$ ,  $P_{70} = 24.98$ ,  $P_{75} = 25$ ,  $P_{80} = 26.95$ ,  $P_{85} = 27.8$ ,  $P_{90} = 29.7$ ,  $P_{95} = 30$ ,  $P_{99} = 34.85$ ,  $\Delta_1 = 0.6574$ ,  $\Delta_2 = 0.6461$ ,  $\Delta_3 = 0.6372$ ,  $\Delta_4 = 0.6330$ ,  $\Delta_5 = 0.6285$ ,  $\Delta_6 = 0.6266$ ,  $\Delta_7 = 0.6217$ ,  $\Delta_8 = 0.6064$ ,  $\Delta_9 = 0.6394$ ,  $\Delta_{10} = 0.6722$ ,  $\Delta_{11} = 0.67030$ ,  $\Delta_{12} = 0.66574$ ,  $\Delta_{13} = 0.6432$ ,  $\Delta_{14} = 0.6326$ ,  $\Delta_{15} = 0.66635$ ,  $\Delta_{16} = 0.6634$ ,  $\Delta_{17} = 0.6715$ ,  $\Delta_{18} = 0.6662$ ,  $\Delta_{19} = 0.66546$ ,  $\Delta_{20} = 0.6528$ ,  $\Delta_{21} = 0.6181$ ,

**Table 1: MSEs and PREs of Existing and Proposed Estimators**

Estimators	MSE	PRE	Estimators	MSE	PRE
$t_0$	53893.89	100	$t_R$	2943.71	183.2344
<b>Kadilar and Cingi<sup>7</sup> Estimator 1</b>			<b>Subramani<sup>15</sup> Estimator</b>		
$t_{KCI}$	2887.46	186.804	$t_S$	2389.24	225.7576
<b>Bhat et al.<sup>2</sup> Estimators</b>					
$t_{B1}$	2330.10	231.4875	$t_{B6}$	2191.71	246.1042
$t_{B2}$	2297.74	234.7476	$t_{B7}$	2078.86	259.4638
$t_{B3}$	2258.56	238.8199	$t_{B8}$	2041.82	264.1707
$t_{B4}$	2236.84	241.1388	$t_{B9}$	1999.23	269.7984
$t_{B5}$	2215.55	243.456	$t_{B10}$	1999.24	269.797
<b>Mulli et al.<sup>10</sup> Estimators</b>			<b>Proposed Estimators</b>		
$t_{J1}$	1993.16	270.62	$t_{A1}$	1958.19	275.4528
$t_{J2}$	1993.57	270.5644	$t_{A2}$	1960.58	275.1171
$t_{J3}$	1995.33	270.3257	$t_{A3}$	1963.75	274.6729

$t_{J4}$	1998.26	269.9293	$t_{A4}$	1965.65	274.4074
$t_{J5}$	1994.76	270.403	$t_{A5}$	1967.96	274.0853
$t_{J6}$	1995.69	270.2769	$t_{A6}$	1969.03	273.9364
$t_{J7}$	1995.17	270.3474	$t_{A7}$	1972.02	273.5211
$t_{J8}$	1993.16	270.62	$t_{A8}$	1983.63	271.9202
$t_{J9}$	1994.01	270.5047	$t_{A9}$	1962.86	274.7975
$t_{J10}$	1996.71	270.1389	$t_{A10}$	1957.84	275.5021
$t_{J11}$	1993.79	270.5245	$t_{A11}$	1957.71	275.5204
$t_{J12}$	1993.77	270.5372	$t_{A12}$	1957.18	275.5950
$t_{J13}$	1995.50	270.3027	$t_{A13}$	1961.48	274.9908
$t_{J14}$	1994.24	270.4735	$t_{A14}$	1965.84	274.3809
$t_{J15}$	1993.07	270.6322	$t_{A15}$	1957.67	275.5260
$t_{J16}$	1993.08	270.6309	$t_{A16}$	1957.68	275.5246
$t_{J17}$	1994.39	270.4531	$t_{A17}$	1957.79	275.5091
$t_{J18}$	1994.16	270.62	$t_{A18}$	1958.16	275.4571
$t_{J19}$	1993.57	270.5644	$t_{A19}$	1960.05	275.1914
$t_{J20}$	1995.33	270.3257	$t_{A20}$	1958.94	275.3474
$t_{J21}$	1998.26	269.9293	$t_{A21}$	1974.44	273.1858

## Results and Discussion

Using the aforementioned real-life dataset, Table 1 displays the MSEs and PREs of the proposed and existing estimators. The findings showed that, in comparison to the existing estimators, the proposed ones have lower MSEs and greater PREs. This suggests that the proposed estimators have a better chance of generating estimates that are more in line with the study variable's actual population mean.

## Conclusion

In this study, we proposed arithmetic mean estimators of a family of ratio type estimators of finite population variance, the properties (Biases and MSEs) of the proposed estimators were derived and from the results of empirical study, it was obtained that the proposed estimators are more efficient than sample mean estimator, ratio estimator, Kadilar and

Cingi<sup>7</sup> estimator, Subramani<sup>15</sup> estimator, Bhat *et al.*<sup>2</sup> and Muili *et al.*<sup>10</sup> estimators. Hence, the proposed estimators are recommended for use in real life situation.

## Acknowledgement

The author would like to thank, Department of Mathematics, Kebbi State University of Science and Technology Aliero, Nigeria. for their guidance and support to complete this article.

## Funding

No financial supported was received by the authors for the research, authorship and publication of this article.

## Conflict of Interest

The authors declare no conflict of interest.

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